

Makefile, app.rules, FreeRTOSConfig.h for example from:
nanostack/Example/nano_example_n120/

3) There are several procedures to be performed before program the sensors:

-In the folder "/Tools" in NanoStack, you should run the command "make" for the proper functioning of the sensor programmer.

When trying to program the sensor with the command "make program" before the "make" in the file previously described, causes the error:

```
*** [Program] Error 127
```

-You must modify the file app.rules the next line in case of opting for programming from Cygwin.

It is for programming using the USB port.

```
#USB device 0.
```

4) To receive data from the sensors is necessary to read the USB port.

For Windows, a quick alternative is HyperTerminal, which is part of a default Windows installation.

For HyperTerminal, open the program and create a new connection.

The serial port parameters for these applications are:

-115200 bps.

-8 data bits.

-no parity.

-1 stop bit.

-Flow control should be disabled.